

Local Performance of the  
 $(\mu/\mu_V, \lambda)$ -ES  
in a Noisy Environment

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# Contents of this presentation

- Noisy Optimization
  - The  $(\mu/\mu_V, \lambda)$ -ES algorithm
  - Introducing a performance measure
  - Discussing the results
  - Conclusions & Future Work
-

# Noisy Optimization



- Noise is a constant companion in our life
- Specifically to optimization problems it can come from various sources
  - Measurement errors
  - Stochastic simulation
  - User interaction
- Consequences
  - Reduced convergence velocity
  - Inability to reach the global optimum

# Noisy Optimization



- Nature itself is a noisy environment - Evolutionary Algorithms are nature inspired models and thus perceived to be robust with respect to noise
- Research on GA
  - J.M. Fitzpatrick and J. J. Grefenstette. 1988. „Genetic Algorithms in Noisy Environments”
  - B. L. Miller and D. E. Goldberg. 1997. „Genetic Algorithms, Selection Schemes, and the Varying Effects of Noise”
  - M. Rattray and J. Shapiro. 1997. „Noisy Fitness Evaluation in Genetic Algorithms and the Dynamics of Learning”
- Research on ES
  - I. Rechenberg. 1973. „Evolutionstrategie: Optimierung Technischer Systeme nach den Prinzipien der biologischen Evolution“
  - H.-G. Beyer. 1993. „Toward a Theory of Evolution Strategies: Some Asymptotical Results from the  $(1,\lambda)/(1+\lambda)$ -Theory“
  - U. Hammel and T. Bäck. 1994. „Evolution Strategies on Noisy Functions. How to Improve Convergence Properties”

# Noisy Optimization

- Empirical evidence shows that a population of solutions weakens the effect of noise
- Infinitely large population can remove the effect of noise entirely in some circumstances
  - great! though a little bit „impractical“
- Resampling – the „brute force“ approach
  - decrease in efficiency
- Balance between Population size and Resampling

# Noisy Optimization



- Why this work?
  - Empirical evidence showed that larger populations helped mitigating the effect of noise, yet..
  - ...analysis of the ES was restricted to 1 parent versions!
  - Can the efficiency of the  $(1+1)$ -ES be topped in a noisy environment?
  - Is Genetic Repair still present when optimizing under noise?
  - Does the ES benefit from larger populations in the same way that the GA does?

# The $(\mu/\mu_V, \lambda)$ -ES algorithm

- $\mu$  parents,  $\lambda$  offsprings
- Comma notation
- Recombination
- Algorithm flow

1. Initialize  $\mu$  parents

2. Compute the centroid  $\langle x \rangle = \frac{1}{\mu} \sum_{i=1}^{\mu} x^{(i)}$

3. Create  $\lambda$  offsprings  $y^{(i)} = \langle x \rangle + z^{(i)}$ ,  $z^{(i)} = N(0, \sigma^2)$ ,  $i = 1, \dots, \lambda$

4. Replace parents with  $\mu$  best from  $y$

5. Continue with 2. until a stop criterion is satisfied

# Fitness environment

- Quadratic Sphere

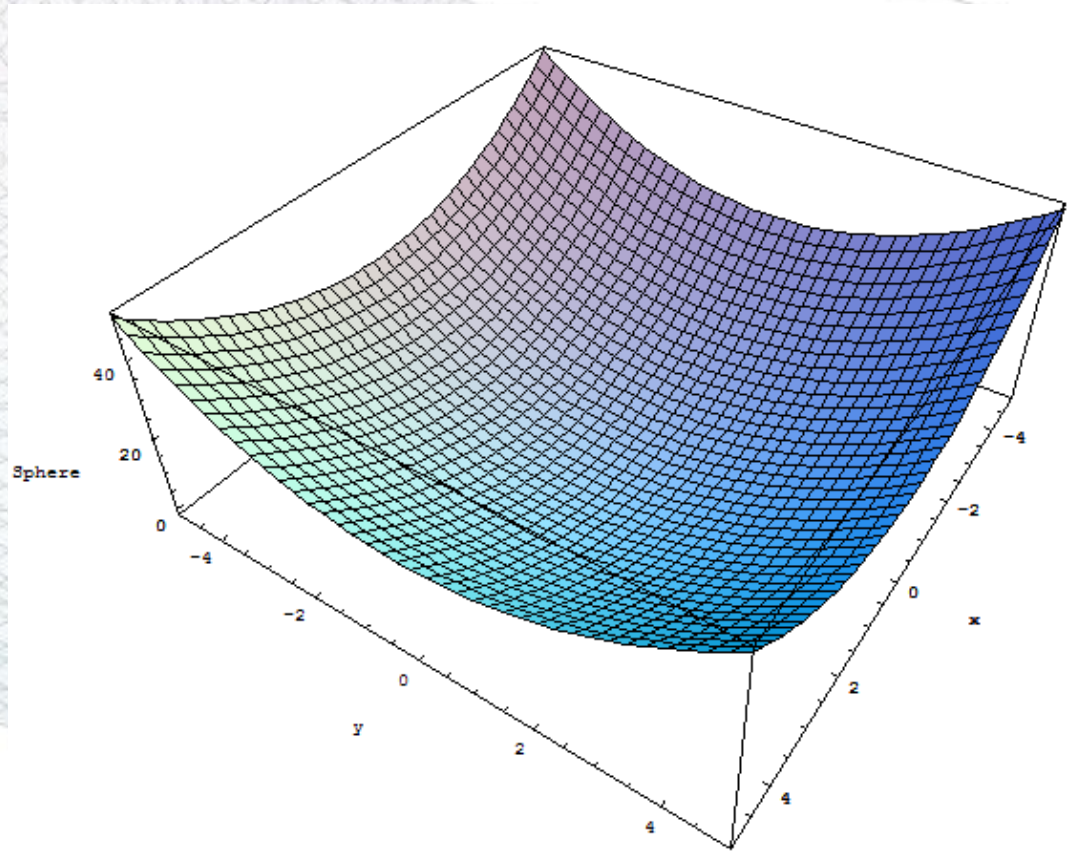
$$f(x) = \sum_{i=1}^N (\hat{x}_i - x_i)^2$$

- Introducing noise

$$\sigma_\varepsilon \delta, \quad \delta = N(0,1)$$

- Perceived fitness

$$f(x) + \sigma_\varepsilon \delta$$



Two dimensional noiseless Sphere with optimum at (0,0)

# Introducing a performance measure

- Fitness advantage

$$q_x(z) = f(x) - f(x+z)$$

- Measurement of local performance

- Progress rate  $\varphi$

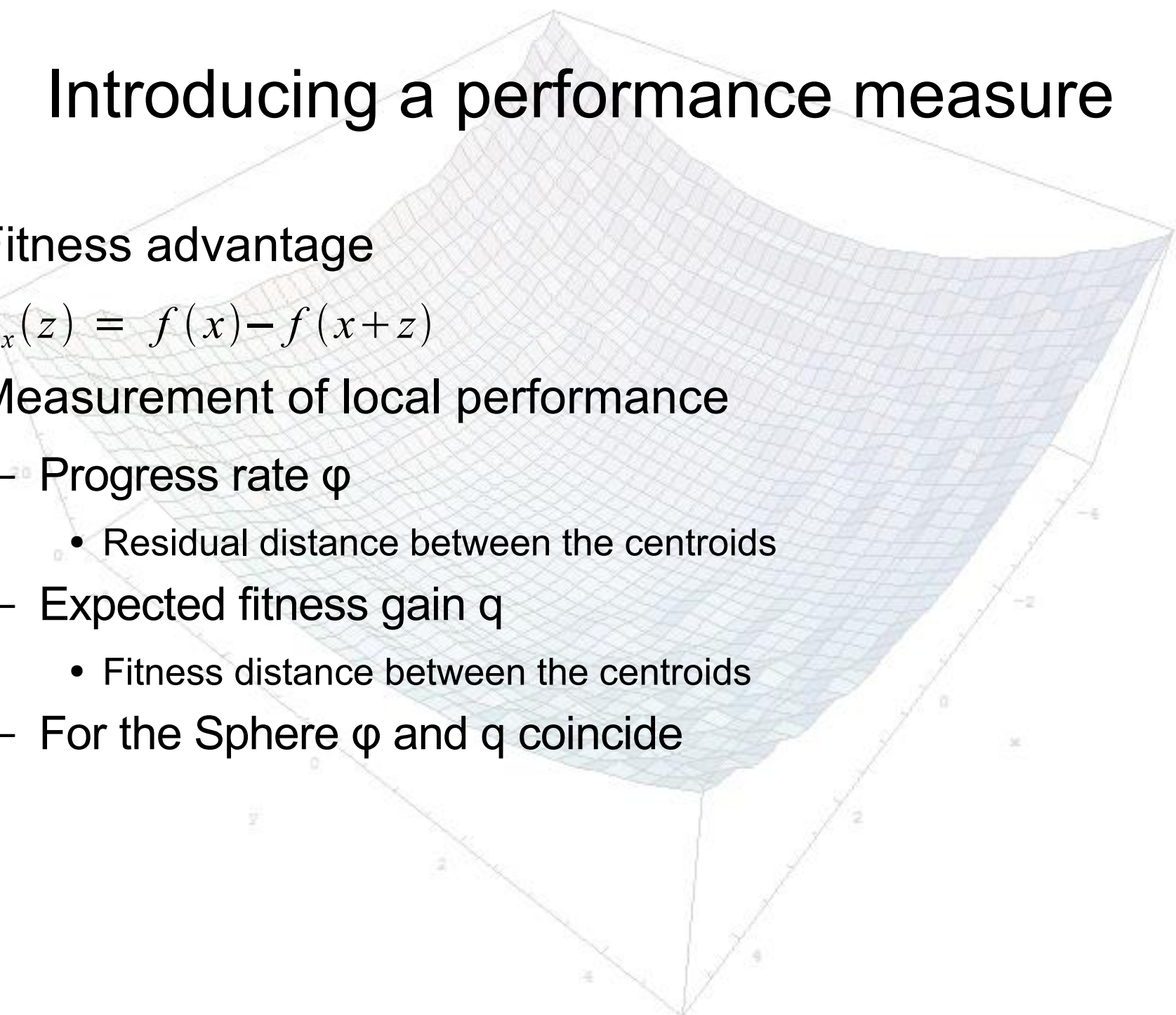
- Residual distance between the centroids

- Expected fitness gain  $q$

- Fitness distance between the centroids

- For the Sphere  $\varphi$  and  $q$  coincide

Fig. 2



# Introducing a performance measure

- Separating mutation vector  $z$

$$z_A = \sigma(z_1, 0, \dots, 0)^T$$

$$z_B = \sigma(0, z_2, \dots, z_N)^T$$

- Introduce normalized quantities

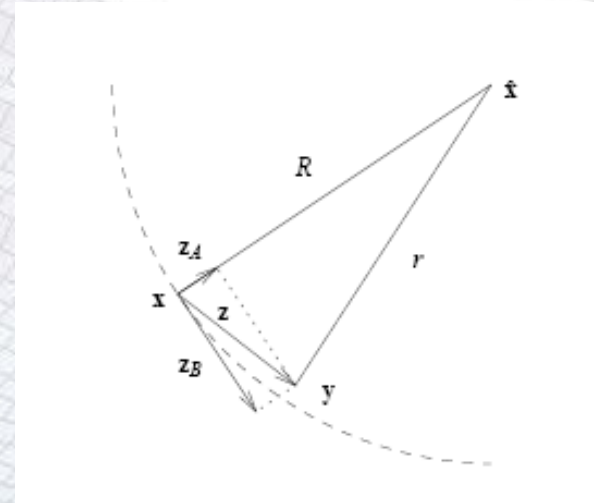
$$\sigma^* = \sigma \frac{N}{R}, \quad \sigma_\varepsilon^* = \sigma_\varepsilon \frac{N}{2R^2}, \quad q_x^*(z) = q_x(z) \frac{N}{2R^2}$$

- The normalized fitness advantage becomes

$$q^*(z) = \sigma^* z_1 - \frac{\sigma^{*2}}{2N} z_1^2 - \frac{\sigma^{*2}}{2N} \sum_{i=2}^N z_i^2 \approx \sigma^* z_1 - \frac{\sigma^{*2}}{2} \quad \text{für } N \rightarrow \infty$$

- The perceived normalized fitness advantage thus is

$$q^*(z) + \sigma_\varepsilon^* \delta = \sigma^* (z_1 + \vartheta \delta) - \frac{\sigma^{*2}}{2}, \quad \vartheta = \frac{\sigma_\varepsilon^*}{\sigma^*} \quad \text{noise-to-signal ratio}$$



# Introducing a performance measure

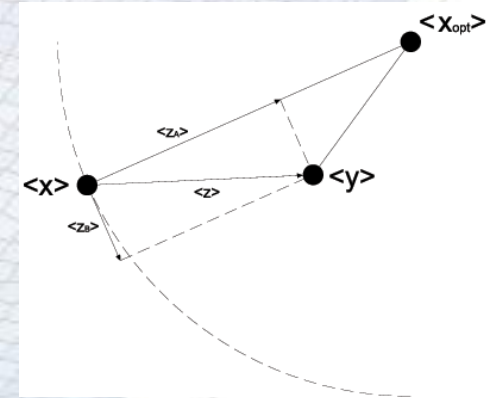
- The progress vector for a population of selected offspring solutions, is the difference between the centroids of the parent population and the selected offsprings
- The expected fitness gain is the expected value of the normalized fitness advantage between the centroids

$$q^*(\langle z \rangle) = \sigma^* \langle z_1 \rangle - \frac{\sigma^{*2}}{2N} \langle z_1 \rangle^2 - \frac{\sigma^{*2}}{2N} \sum_{i=2}^N \langle z_i \rangle^2$$

- The function can be simplified similar to the normalized fitness advantage

$$q^*(\langle z \rangle) \approx \sigma^* \langle z_1 \rangle - \frac{\sigma^{*2}}{2\mu}$$

- The factor  $\mu$  reflects the presence of genetic repair



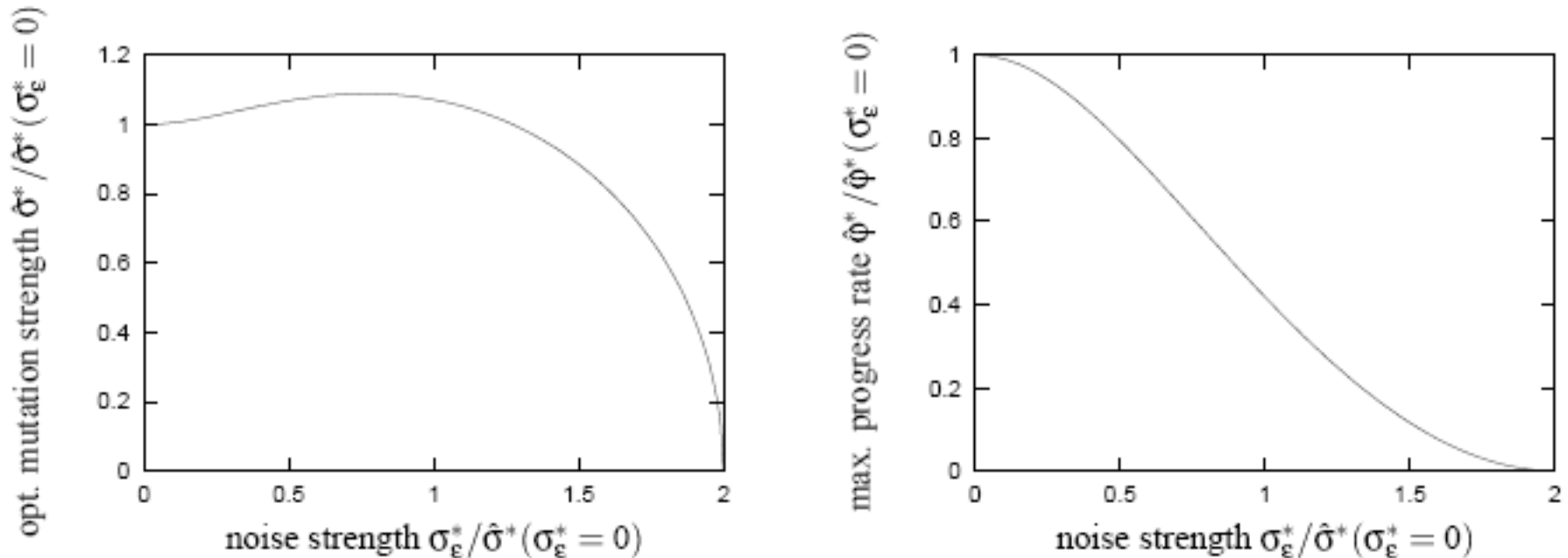
# Introducing a performance measure

- Calculating the expected value of the normalized fitness advantage is quite a challenging task
- The final progress rate law is

$$\varphi^* = \frac{c_{\mu/\mu, \lambda} \sigma^*}{\sqrt{(1+\vartheta^2)}} - \frac{\sigma^{*2}}{2\mu}, \quad c_{\mu/\mu, \lambda} = \frac{\lambda - \mu}{2\pi} \binom{\lambda}{\mu} \int_{-\infty}^{\infty} e^{-x^2} [\Phi(x)]^{\lambda - \mu - 1} [1 - \Phi(x)]^{\mu - 1} dx$$

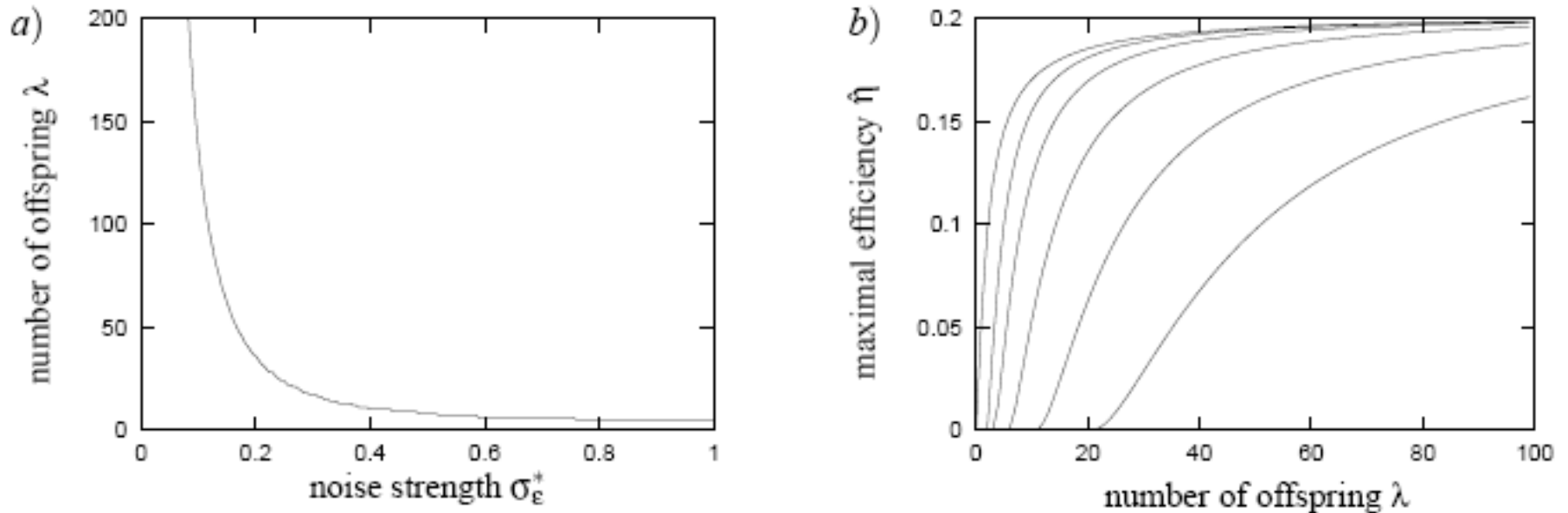
- This is in accordance to the analytical results obtained from the  $(\mu/\mu, \lambda)$ -ES on the noiseless Sphere
- On the noisy Sphere for  $\mu=1$  results of the  $(1, \lambda)$ -ES appear as special cases to the equation obtained here

# Discussing the results



- The  $(\mu/\mu_V\lambda)$ -ES is able to achieve a positive progress rate up to a normalized noise strength of  $2\mu c$  and thus by scaling the parameter  $\mu$  we can deal with any noise strength
- Genetic repair is present and allows for higher mutation strengths, which in turn decreases the noise-to-signal ratio

# Discussing the results



- From a) we can see that in the presence of noise the  $(2/2, 6)$ -ES is more efficient compared to the  $(1+1)$ -ES for noise strength  $> 0.59$  already
- In b) we can see the efficiency of the  $(\mu/\mu_V, \lambda)$ -ES for various normalized noise strengths (0, 1, 2, 4, 8, 16).
- By increasing the number of offspring we asymptotically close the gap to the max efficiency of 0.202 in the absence of noise

# Conclusions



- We could show that by increasing the population size we can remove the effects of noise entirely
- Genetic Repair is present, this makes it possible to choose higher mutation strengths and thus decrease the noise to signal ratio
- The efficiency of the  $(1+1)$ -ES could be exceeded by a multi-parent strategy with recombination for small population sizes already

# Future Work



- Analyze the performance of the  $(\mu/\mu_V, \lambda)$ -ES in other fitness environments and finite-dimensional parameter spaces
- Extend the analysis to dominant rather than intermediate recombination
- Investigate the effects of noise on the behavior of mutation strength adaption schemes



Thank you for your time